



## **Predictive Coding for Robot Cognition**

Yukie Nagai NICT / Bielefeld University

## **Take Home Messages**

- Predictive coding/learning is a powerful unified theory for designing cognitive mechanisms in robots.
  - Various dynamics of cognitive development can be reproduced based on the theory.
- Consciousness emerge as a byproduct of the development of cognition functions.
  - Cognitive behaviors require internal models which produce consciousness.





## **Underlying Mechanism?**

**Self** cognition (from 24 mo) [Amsterdam, 1972; Povinelli et al., 1996]



Helping others (from 14 mo)

[Warneken & Tomasello, 2006]



Joint attention (from 12 mo)

[Butterworth & Jarrett, 1991] [Moore et al., 1996] [Brooks & Meltzoff, 2002]

**Unified theory** 

Reading intention (from 6 mo)

[Woodward, 1998] [Gergely et al., 1995]

Imitation (from 0 mo)

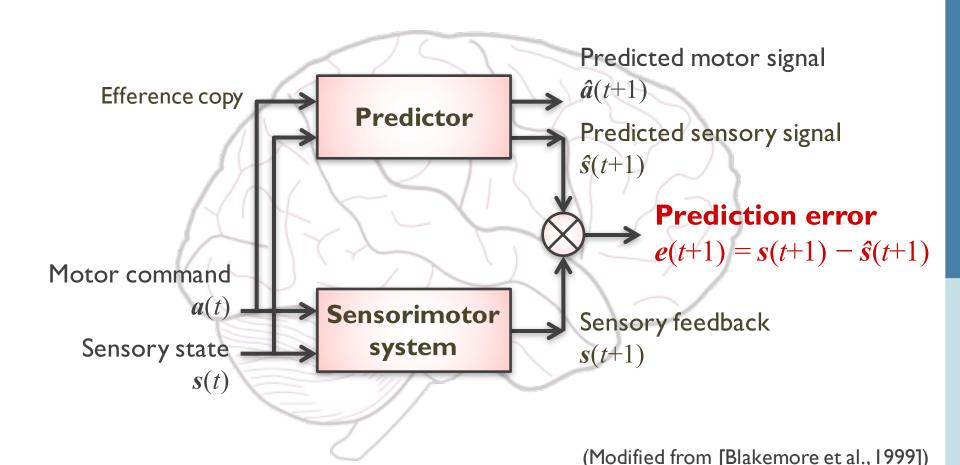
[Meltzoff & Moore, 1977] [Heyes, 2001] Expressing emotion (from 6 mo)

[Bridges 1930; Lewis, 2007]

### Our Hypothesis: Predictive Learning

[Nagai & Asada, IROS-WS 2015]

Minimization of prediction error e(t+1) leads to cognitive development during early infancy.



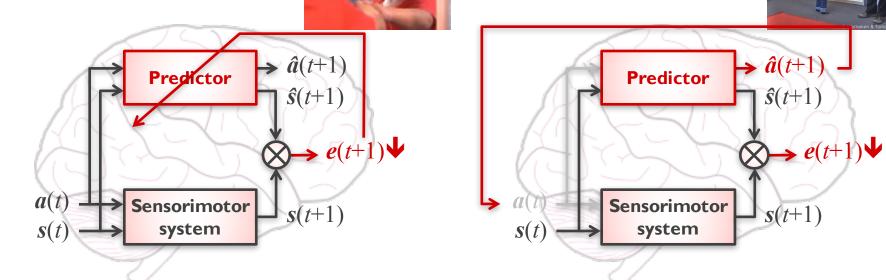
## Our Hypothesis: Predictive Learning

[Nagai & Asada, IROS-WS 2015]

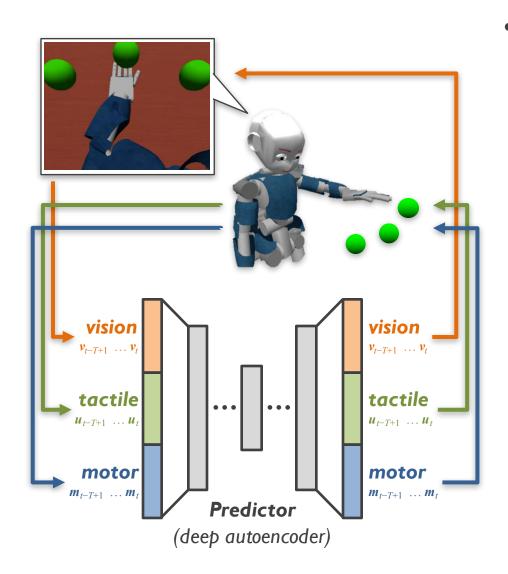
Minimization of prediction error e(t+1) leads to cognitive development during early infancy.

- (a) Update the predictor through sensorimotor experiences
  - → Self-other cognition, goal-directed action, etc.

- (b) Execute a predicted action in response to others' action
  - → Imitation, helping action, etc.

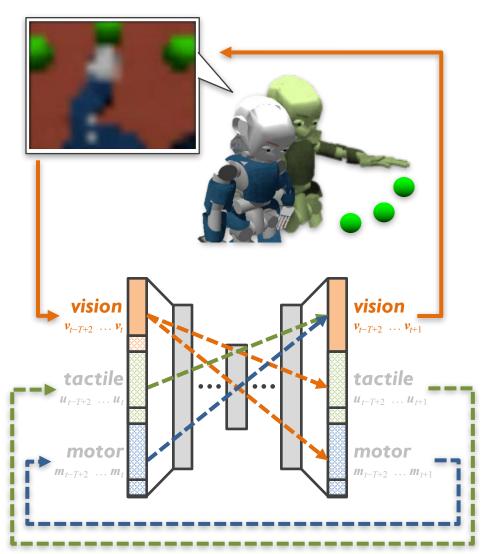


# Multimodal Predictive Learning for Action Production and Perception



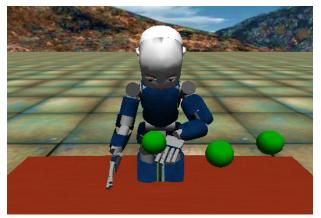
- Predictive learning to integrate multimodal signals enables infants to recall own motor experiences while observing others' action (i.e., mirror neuron system).
  - Motor learning: integrating
     visual v, tactile u, and motor m
     signals

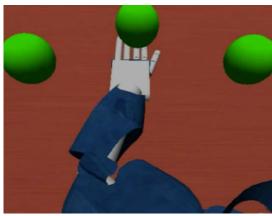
# Multimodal Predictive Learning for Action Production and Perception



- Predictive learning to integrate multimodal signals enables infants to recall own motor experiences while observing others' action (i.e., mirror neuron system).
  - Motor learning: integrating
     visual v, tactile u, and motor m
     signals
  - Action observation: generating imaginary u and m from actual
     v > better prediction of v

### Results 1: Prediction of Others' Goal







Actual image

Predicted image

Predicted image	Classifications of prediction
4	Correct goal
	Incorrect goal
_	No goal

### Input/output signals:

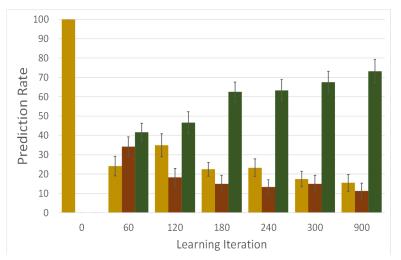
- Vision: camera image (30)
- Tactile: on/off (3)
- Motor: joint angles of shoulder and elbow (4)

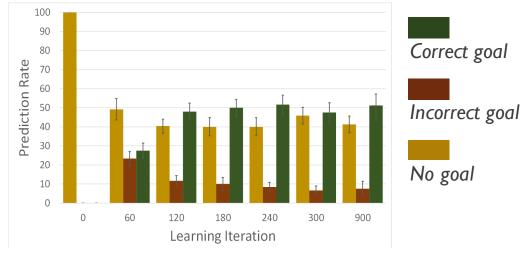
[Copete, Nagai, & Asada, ICDL-EpiRob 2016]

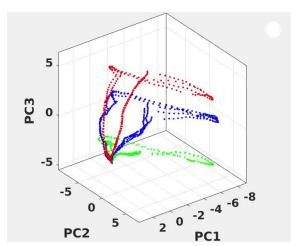
# Result 2: Motor Experience Improved Accuracy of Prediction

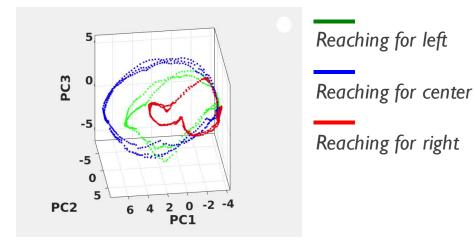
W/ motor experience

W/o motor experience (only observation)



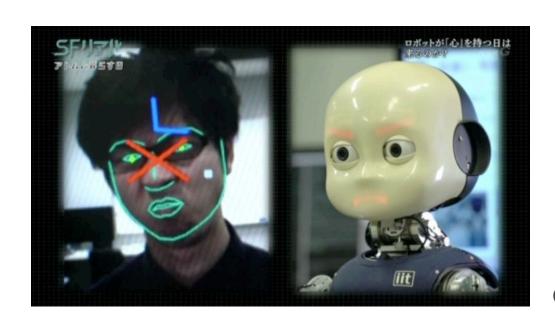


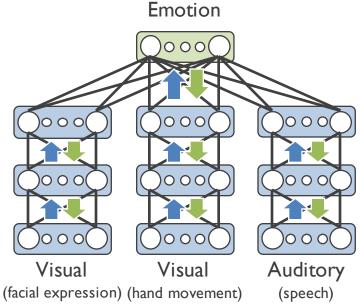




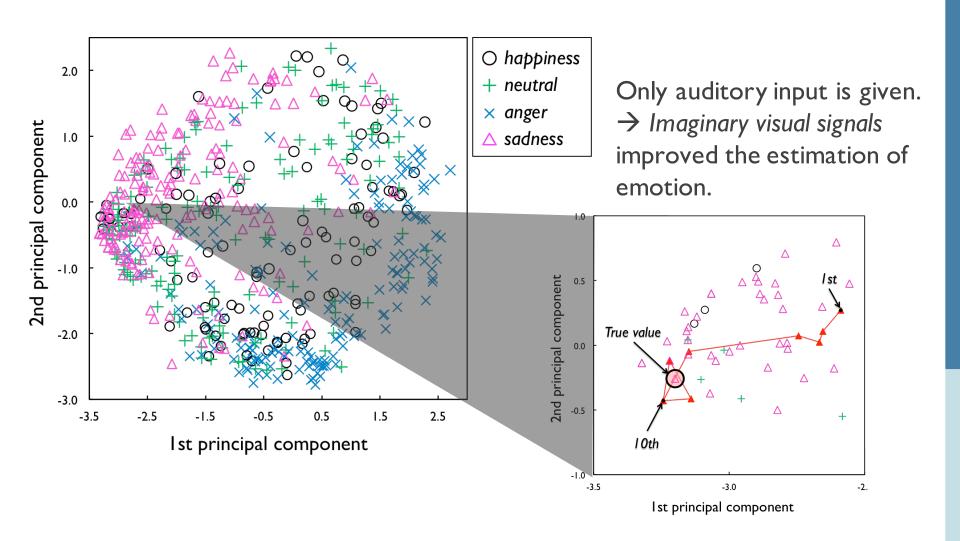
## Multimodal Predictive Learning for Emotion Imitation

- Emotion is perceived through inference of interoceptive and exteroceptive signals. [Seth et al., 2012]
- Predictive learning of multimodal signals enables infants to estimate and imitate others' emotion by putting themselves in others' shoes (i.e., mirror neuron system).





## Prediction of Sensory Signals Improves the Estimation of Emotion



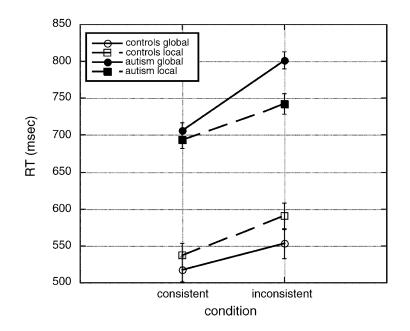
[Horii, Nagai, & Asada, Paladyn 2016]

# Different Level of Consciousness in Autism Spectrum Disorder

### What Letters Can You See?

S S S S S S SSSSSS SSS S S S

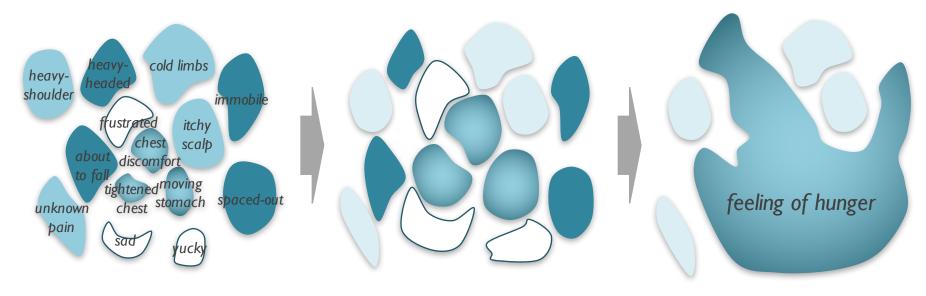
 People with ASD recognize the local letter quicker than the global letter. [Behrmann et al., 2006]



## Difficulty in Feeling Hunger in ASD

• Feeling of hunger is hard to be recognized and requires conscious process of selecting and integrating proper sensory signals.

[Ayaya & Kumagaya, 2008]



- Equally perceive multimodal sensations
- 2. Enhance hunger-relevant signals while diminishing hunger-irrelevant signals
- Recognize hunger by integrating relevant signals

: likely relevant to hunger

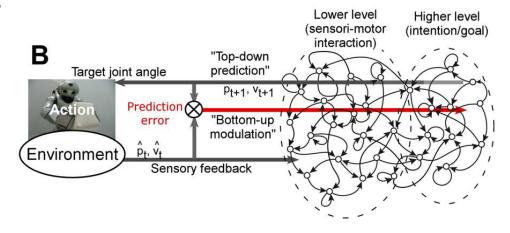
: likely irrelevant to hunger

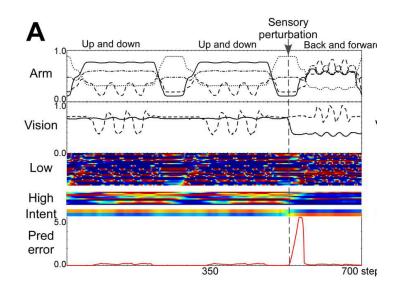
: limited to hunger

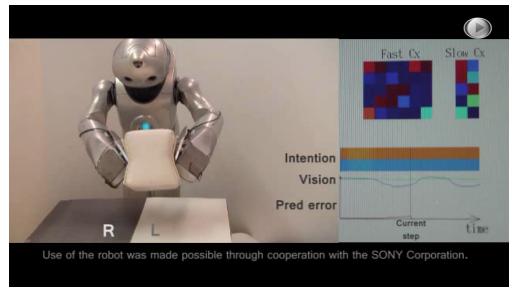
\_\_\_\_:psychological

# Schizophrenia-like Behaviors Generated by Modifications in Neural Network [Yamashita & Tani, 2012]

- Multiple timescale recurrent neural network (MTRNN)
  - Lower layer (fast context):
     behavioral primitives
  - Higher layer (slow context):
     combinations of primitives

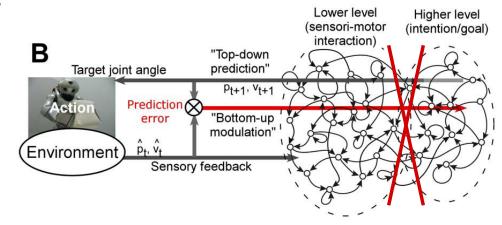


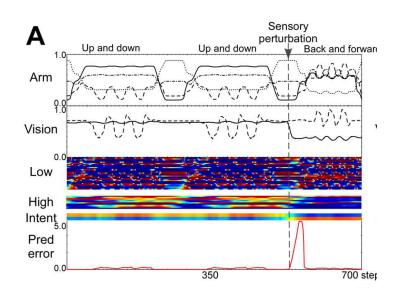


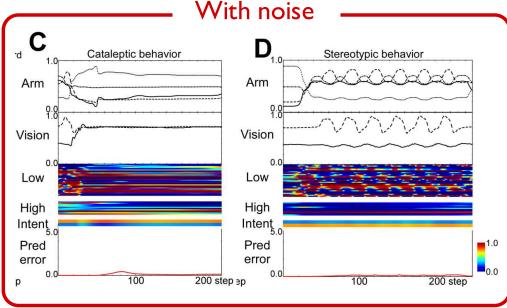


# Schizophrenia-like Behaviors Generated by Modifications in Neural Network [Yamashita & Tani, 2012]

- Multiple timescale recurrent neural network (MTRNN)
  - Lower layer (fast context):behavioral primitives
  - Higher layer (slow context):
     combinations of primitives







## **Atypical Visual Perception in ASD**



## **Take Home Messages**

- Predictive coding/learning is a powerful unified theory for designing cognitive mechanisms in robots.
  - Various dynamics of cognitive development can be reproduced based on the theory.
- Consciousness emerge as a byproduct of the development of cognition functions.
  - Cognitive behaviors require internal models which produce consciousness.
- Different levels of consciousness in ASD provide deeper insights into the roles of consciousness.

#### Thank You!

### **Osaka University**

- Minoru Asada
- Jimmy Baraglia
- Takato Horii
- Shibo Qin
- Jorge L. Copete
- Konstantinos Theofilis
- Jyh-Jong Hsieh, et al.

### **University of Tokyo**

- Shinichiro Kumagaya
- Satsuki Ayaya









yukie@nict.go.jp http://developmental-robotics.jp